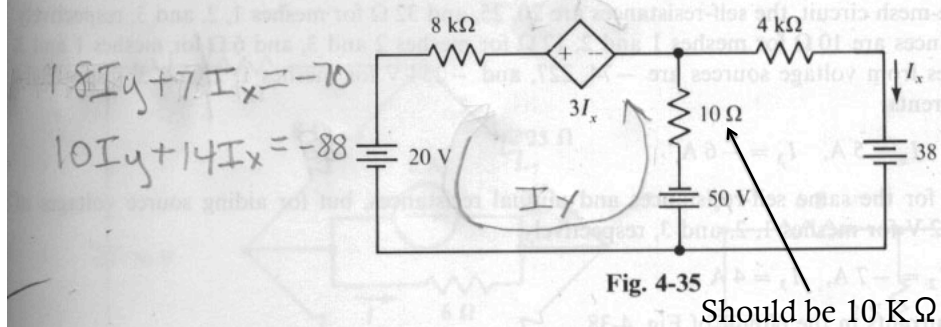


Bug in Homework

4.40 Determine I_x in the circuit of Fig. 4-35.

Ans. -4.86 mA



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Distribution of charge and voltage on multiple capacitors

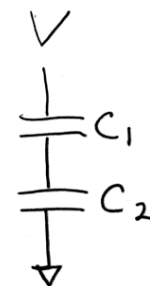
- To find the voltage on capacitors in series
 - Find total effective capacitance C_{Total}
 - Charge will be $Q_{\text{Total}} = C_{\text{Total}} V$
 - Same charge will be on all caps (Kirchoff's Current Law)
 - Voltage will be distributed inversely to capacitance

$$Q_{\text{Total}} = VC_{\text{Total}}$$

$$Q_{\text{Total}} = Q_1 = Q_2$$

$$V_1 = \frac{Q_1}{C_1} = \frac{Q_{\text{Total}}}{C_1} = \frac{C_{\text{Total}}}{C_1} V$$

$$V_2 = \frac{Q_2}{C_2} = \frac{Q_{\text{Total}}}{C_2} = \frac{C_{\text{Total}}}{C_2} V$$



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Distribution of charge and voltage on multiple capacitors

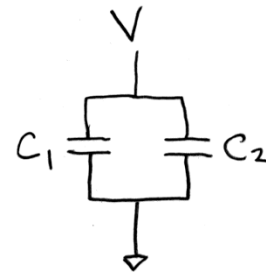
- To find the charge in capacitors in parallel
 - Find total effective capacitance C_{Total}
 - Charge will be $Q_{\text{Total}} = C_{\text{Total}} V$
 - Same voltage will be on all caps (Kirchoff's Voltage Law)
 - Q_{Total} will be divided proportionally to capacitance

$$Q_{\text{Total}} = VC_{\text{Total}} = Q_1 + Q_2$$

$$V = V_1 = V_2$$

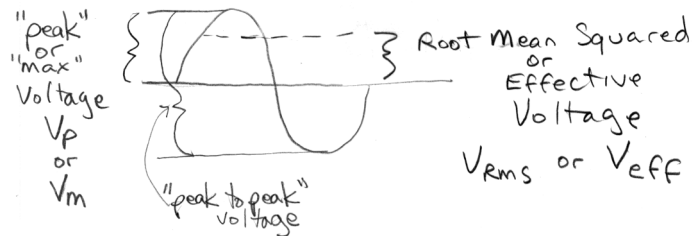
$$Q_1 = VC_1$$

$$Q_2 = VC_2$$



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Definitions of Sinusoidal Amplitude



$$V_{\text{RMS}} = \frac{V_P}{\sqrt{2}}$$

- Average power = $V_{\text{RMS}} \times I_{\text{RMS}}$, when they are in-phase (resistor).
- Since $\sin^2 + \cos^2 = 1$, each has an average value of $\frac{1}{2}$, and the V_{RMS} is V_P divided by $\sqrt{2}$.
- If V_{RMS} and I_{RMS} are 90° out-of-phase, the average power is zero, as they are in a coil or a capacitor, so the LC branch does not dissipate power and can “ring” forever.

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Let's prove those last statements

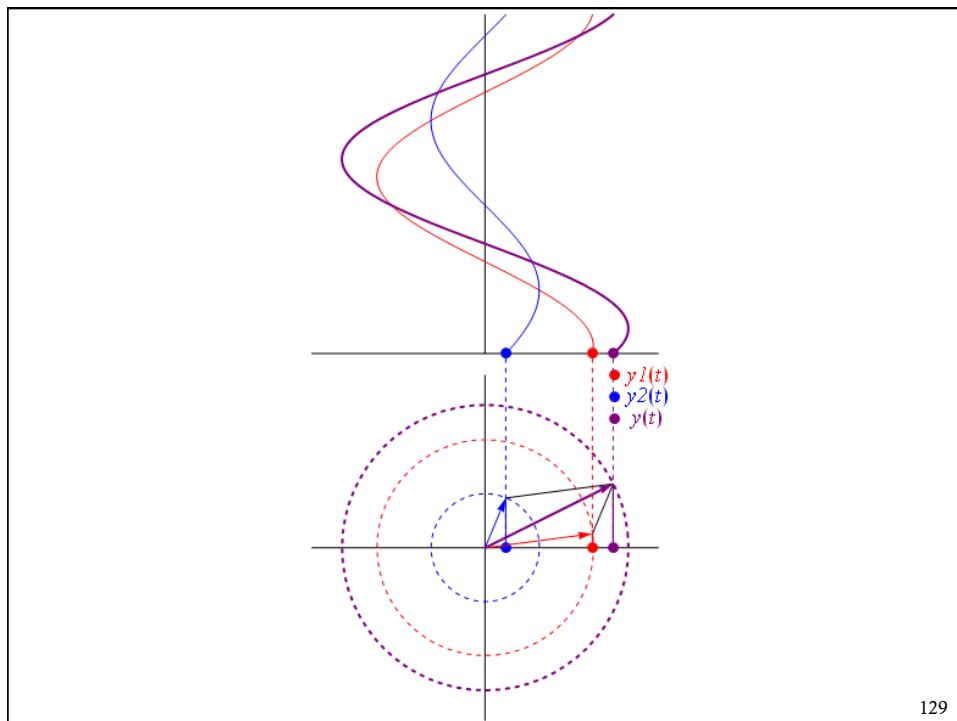
Just as we showed that when V_{RMS} and I_{RMS} are in-phase

$$\cos^2(\omega t) = \frac{1 + \cos(2\omega t)}{2}, \text{ whose average (DC) value of } \frac{1}{2},$$

when V_{RMS} and I_{RMS} are 90° out-of-phase,

$$\begin{aligned} \cos(\omega t)\sin(\omega t) &= \left(\frac{e^{j\omega t} + e^{-j\omega t}}{2}\right) \left(\frac{e^{j\omega t} - e^{-j\omega t}}{2j}\right) \\ &= \frac{e^{j2\omega t} - e^{-j2\omega t} + e^0 - e^0}{4j} \\ &= \frac{\sin(2\omega t)}{2}, \text{ whose average value is zero.} \end{aligned}$$

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Phasor Notation Ambiguity

- In electronics, complex exponentials are described unambiguously with shorthand notation

$$re^{j(\omega t + \theta)} \Rightarrow "r \angle \theta"$$

- Unfortunately when applied to real voltages and currents, the same notation is used variously to mean sine or cosine, peak or RMS. Thus, $A \angle \theta$ may mean

$$v(t) = \frac{A}{\sqrt{2}} \sin(\omega t + \theta)$$

or

$$v(t) = A \cos(\omega t + \theta)$$

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Phasor Notation Ambiguity (cont...)

- This ambiguity is allowed to continue because linear systems change only magnitude and phase.
- Thus a given network of coils, capacitors, and resistors will cause the same relative change in

$$v(t) = \frac{A}{\sqrt{2}} \sin(\omega t + \theta)$$

as it does in

$$v(t) = A \cos(\omega t + \theta)$$

so it doesn't matter which definition of $A \angle \theta$ you use for real signals, so long as you are consistent.

see my Phasor Notation Manifesto on website

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Systems modeled as Filters

- Has input and output signals (functions of time).
- Most electronic systems use voltages as inputs and outputs.
- Has a “transfer function” $H(\omega)$ in the frequency domain.
- $H(\omega)$ determines what happens to $e^{j\omega t}$, and thus any signal.

$$V_{in}(t) \rightarrow \boxed{H(\omega)} \rightarrow V_{out}(t) \quad H(\omega) = \frac{V_{out}(t)}{V_{in}(t)}$$

- Consider system consisting of a voltage divider.
- Divider can now use complex impedances.

$$V_{in}(t) \rightarrow \boxed{Z_2} \rightarrow V_{out}(t) \quad H(\omega) = \frac{Z_1}{Z_1 + Z_2}$$

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Example: RC High-Pass Filter

$$V_{in}(t) \rightarrow \boxed{C} \rightarrow V_{out}(t) \quad H(\omega) = \frac{V_{out}(t)}{V_{in}(t)}$$

$$H(\omega) = \frac{R}{R + \frac{1}{j\omega C}} = \frac{j\omega RC}{1 + j\omega RC}$$

At high frequencies, acts like a piece of wire.

$$H(\omega) \cong 1, \quad \omega \gg \frac{1}{RC}$$

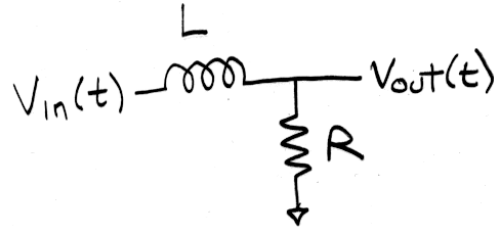
At low frequencies, attenuates and differentiates.

$$H(\omega) \cong j\omega RC, \quad \omega \ll \frac{1}{RC}$$

Key frequency is reciprocal of time constant RC .

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Example: LC Low-Pass Filter



$$H(\omega) = \frac{V_{\text{out}}(t)}{V_{\text{in}}(t)}$$

$$H(\omega) = \frac{R}{R + j\omega L} = \frac{1}{1 + j\omega \frac{L}{R}}$$

At low frequencies, acts like a piece of wire.

$$H(\omega) \cong 1, \quad \omega \ll \frac{R}{L}$$

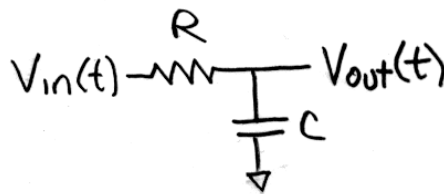
At high frequencies, attenuates and integrates.

$$H(\omega) \cong \frac{R}{j\omega L}, \quad \omega \gg \frac{R}{L}$$

Key frequency is reciprocal of time constant L/R .

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Example: RC Low-Pass Filter



$$H(\omega) = \frac{V_{\text{out}}(t)}{V_{\text{in}}(t)}$$

$$H(\omega) = \frac{1}{R + \frac{1}{j\omega C}} = \frac{1}{1 + j\omega RC}$$

At low frequencies, acts like a piece of wire.
(assuming no current at output)

$$H(\omega) \cong 1, \quad \omega \ll \frac{1}{RC}$$

At high frequencies, attenuates and integrates.

$$H(\omega) \cong \frac{1}{j\omega RC}, \quad \omega \gg \frac{1}{RC}$$

Key frequency is reciprocal of time constant RC .

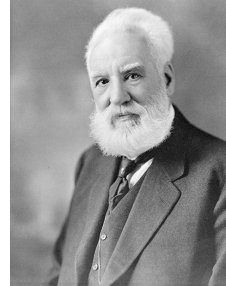
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Decibels – a ratio

1 Bell = order of magnitude in power = 10 dB

$$\text{dB} = 10 \log\left(\frac{P_1}{P_2}\right)$$

Alexander Graham Bell



e.g. if $P_1 = 100\text{w}$ and $P_2 = 1\text{w}$
we have a 20 dB increase
from P_2 to P_1

$$10 \log\left(\frac{100\text{w}}{1\text{w}}\right) = 20 \text{ dB}$$

↑
pure number

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Decibels are ratios of power, but we mainly use voltage

since power \propto voltage²
10 \times the voltage \rightarrow 100 \times power
or 20 dB

So a dynamic Range of 40 dB

↓

$$\frac{V_{\text{BIGGEST}}}{V_{\text{SMALLEST}}} = 100 \quad \frac{P_{\text{BIGGEST}}}{P_{\text{SMALLEST}}} = 10^4$$

(as in the mikes in our lab)

$$\text{dB} \equiv 10 \log\left(\frac{P_1}{P_2}\right) = 20 \log\left(\frac{V_1}{V_2}\right)$$

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Dynamic Range

- The useful range in a system, from smallest to largest signal, generally expressed in dB.
- *Analog Systems*: limited by the noise “floor” and by “clipping” at the maximum voltage.
- *Digital Systems*: limited by the number of bits representing the signal (as we’ll see later).

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Absolute measures using decibels

dBm is power relative to 1mW
 So 1mW = 0dBm
 1W = 30dBm

dBu is power into 600Ω
 (professional low impedance audio)
 0dBu = 1mW into 600Ω = .775V

$$\frac{V^2}{R} = 1\text{mW} \quad V = \sqrt{0.6} = .775\text{V}$$

studios run at +4dBu

$$+4\text{dBu} = 10^{\frac{0.4}{2}} \times .775\text{V} = 1.23\text{V}$$

divide by 2 because $V \propto \sqrt{P}$

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More absolute measures using decibels

dBV is voltage into high impedance
(consumer audio)

$$0\text{dBV} = 1\text{V}$$

tends to run at -10dBV

$$-10\text{dBV} = 10^{-\frac{10}{20}} \times 1\text{V} = 0.316\text{V}$$

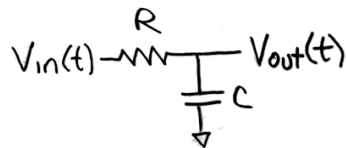
dB SPL (sound pressure level)

0dB SPL = threshold human hearing
our mike is 54dB SPL
or $10^{5.4}$ x threshold in power

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Magnitude and Phase of a Filter

Recall low-pass filter:



$$H(\omega) = \frac{V_{\text{out}}(t)}{V_{\text{in}}(t)} = \frac{1}{1 + j\omega RC}$$

$$V_{\text{out}}(t) = H(\omega)V_{\text{in}}(t)$$

At cut-off frequency, $\omega_c = 1/RC$,

$$H(\omega) = \frac{1}{1+j} \cdot \frac{1-j}{1-j} = \frac{1-j}{2}$$

stationary phasor
changes magnitude
and phase of signal

Magnitude (Attenuation)

$$|H(\omega)| = \left| \frac{1-j}{2} \right| = \frac{1}{\sqrt{2}}$$

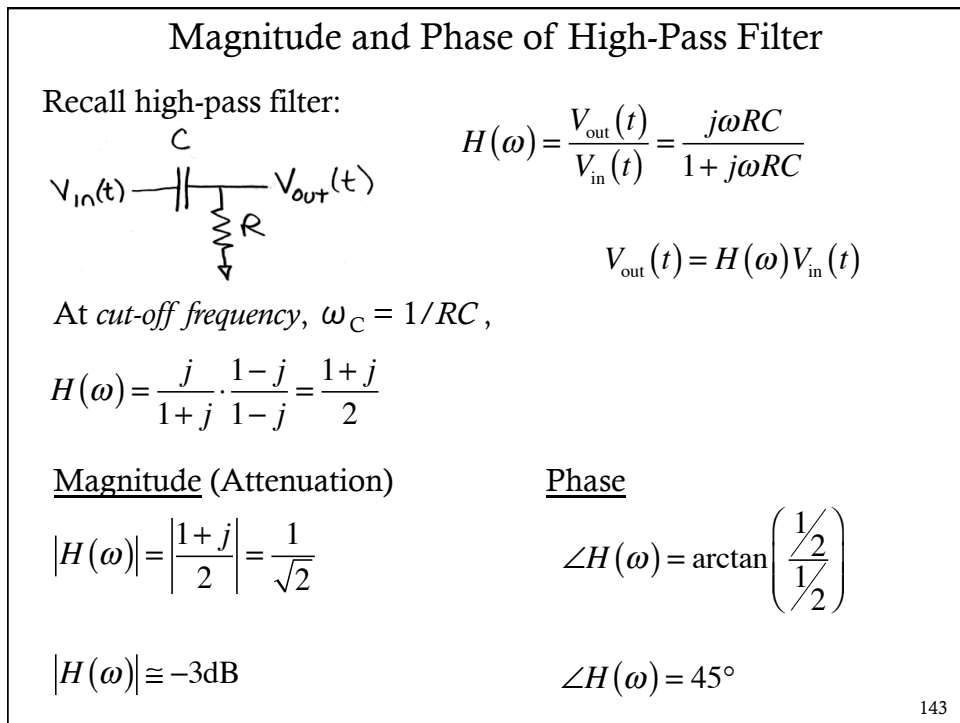
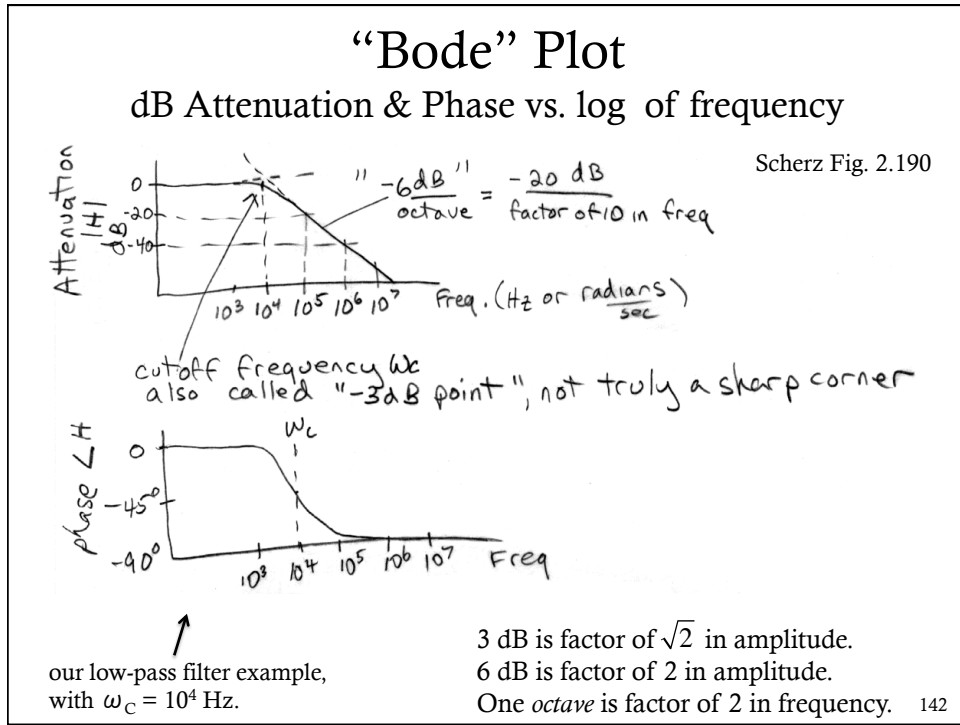
$$|H(\omega)| \cong -3\text{dB}$$

Phase

$$\angle H(\omega) = \arctan\left(\frac{-1/2}{1/2}\right)$$

$$\angle H(\omega) = -45^\circ$$

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Bode Plot of High-Pass Filter

